# 1 Introduction

In this lecture, we add constructs to the typed  $\lambda$ -calculus that allow working with more complicated data structures, such as pairs, tuples, records, sums and recursive functions. We also provide denotational semantics for these new constructs.

## 2 Recap – The Typed $\lambda$ -Calculus $\lambda^{\rightarrow}$

2.1 Syntax

#### 2.2 Typing Rules

$$\begin{array}{ccc} \Gamma \vdash n : \mathsf{int} & \Gamma \vdash \mathsf{true:bool} & \Gamma \vdash \mathsf{false:bool} & \Gamma \vdash \mathsf{null:unit} & \Gamma, x : \tau \vdash x : \tau \\ & \\ & \\ & \\ & \\ \hline \Gamma \vdash e_0 e_1 : \tau & \\ & \\ \hline \Gamma \vdash (\lambda x : \sigma . e) : \sigma \to \tau \end{array}$$

# 3 Simple Data Structures

Each data structure can be added by extending the syntax of expressions (e), types  $(\tau)$  and values (v). The evaluation contexts (E) will also need to be extended, and evaluation and type derivation rules added to work with the new syntax.

### 3.1 Pairs

Syntax:

For every added syntactic form, we observe that we have expressions that *introduce* the form, and expressions that *eliminate* the form. In the case of pairs, the introduction expression is  $(e_1, e_2)$ , and the elimination expressions are #1e and #2e.

Evaluation rules:

$$\#1(v_1, v_2) \to v_1 \qquad \#2(v_1, v_2) \to v_2$$

Note that these rules define *eager* evaluation, because we only select from a pair when both elements are already evaluated to a value.

Typing rules:

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2} \qquad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash \#1 \, e : \tau_1} \qquad \frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash \#2 \, e : \tau_2}$$

# 3.2 Tuples

Syntax:

Evaluation rule:

$$\#\mathsf{m}(v_1,\ldots,v_n)\to v_m \qquad (1\le m\le n)$$

Typing rules:

$$\frac{\Gamma \vdash e_i : \tau_i \quad i \in \{1, \dots, n\}}{\Gamma \vdash (e_1, \dots, e_n) : \tau_1 * \dots * \tau_n} \qquad \frac{\Gamma \vdash e : \tau_1 * \dots * \tau_n}{\Gamma \vdash \#\mathsf{m} \, e : \tau_m} \qquad (1 \le m \le n)$$

## 3.3 Records

Syntax:

Evaluation rule:

$$\{x_1 = v_1, \dots, x_n = v_n\} \cdot x_i \to v_i \qquad (1 \le i \le n)$$

Typing rules:

$$\frac{\Gamma \vdash e_i:\tau_i, \ 1 \le i \le n}{\Gamma \vdash \{x_1 = e_1, \dots, x_n = e_n\}: \{x_1:\tau_1, \dots, x_n:\tau_n\}} \qquad \frac{\Gamma \vdash e:\{x_1:\tau_1, \dots, x_n:\tau_n\}}{\Gamma \vdash e.x_i:\tau_i} \qquad (1 \le i \le n)$$

## 3.4 Sums

Sums are useful for representing datatypes that can have multiple forms. For example, a tail of a list can either be another nonempty list or null.

Syntax:

The inL and inR constructs are called *left injection* and *right injection*, respectively. Evaluation rules:

case 
$$(inL_{\tau_1+\tau_2} v)$$
 of  $e_1 \mid e_2 \rightarrow e_1 v$  case  $(inR_{\tau_1+\tau_2} v)$  of  $e_1 \mid e_2 \rightarrow e_2 v$ 

Here  $e_1$  and  $e_2$  are functions and must have the same codomain type in order for the whole case expression to have a type.

Typing rules:

$$\frac{\Gamma \vdash e:\tau_1}{\Gamma \vdash \mathsf{inL}_{\tau_1 + \tau_2} \; e:\tau_1 + \tau_2} \qquad \frac{\Gamma \vdash e:\tau_2}{\Gamma \vdash \mathsf{inR}_{\tau_1 + \tau_2} \; e:\tau_1 + \tau_2} \qquad \frac{\Gamma \vdash e_0:\tau_1 + \tau_2 \quad \Gamma \vdash e_1:\tau_1 \to \tau_3 \quad \Gamma \vdash e_2:\tau_2 \to \tau_3}{\Gamma \vdash \mathsf{case} \; e_0 \; \mathsf{of} \; e_1 \mid e_2:\tau_3}$$

To give an example of the sum type, consider the sum of two unit types, unit + unit. This type has exactly two elements, namely inL null and inR null. We could take this as a definition of the type bool with elements true  $\stackrel{\triangle}{=}$  inL null and false  $\stackrel{\triangle}{=}$  inR null. The statement if b then  $e_1$  else  $e_2$  could then be written as case b of  $\lambda z. e_1 \mid \lambda z. e_2$ .

SML has a construct that is a generalization of the sum type:

$$e ::= \cdots | x_i(e)$$
  
$$\tau ::= \cdots | [x_1 : \tau_1, \dots, x_n : \tau_n]$$

The SML syntax is

datatype t = x1 of t1 | 
$$\dots$$
 | xn of tn

Such datatypes are also called *variants*. The xi are constructors, and must be globally (across all types) unique to avoid confusion as to which type a particular constructor is referring to (in our sum type, the confusion is alleviated by using  $\tau_1 + \tau_2$  subscripts in inLand inR).

## 4 Denotational Semantics

We now give the denotational semantics for type domains of  $\lambda^{\to +*}$ , the strongly-typed  $\lambda$ -calculus with sum and product types.

$$\begin{split} \mathcal{T}\llbracket\tau \to \tau'\rrbracket &\stackrel{\bigtriangleup}{=} & \mathcal{T}\llbracket\tau\rrbracket \to \mathcal{T}\llbracket\tau'\rrbracket\\ \mathcal{T}\llbracket\tau * \tau'\rrbracket &\stackrel{\bigtriangleup}{=} & \mathcal{T}\llbracket\tau\rrbracket \times \mathcal{T}\llbracket\tau'\rrbracket\\ \mathcal{T}\llbracket\tau + \tau'\rrbracket &\stackrel{\bigtriangleup}{=} & \mathcal{T}\llbracket\tau\rrbracket + \mathcal{T}\llbracket\tau'\rrbracket \end{split}$$

As before, our contract for this language is:

$$\rho \models \Gamma \land \Gamma \vdash e: \tau \quad \Rightarrow \quad \mathcal{C}\llbracket e \rrbracket \Gamma \rho \in \mathcal{T}\llbracket \tau \rrbracket.$$

The remaining semantic rules are:

$$\begin{split} \mathcal{C}[\![(e_1, e_2)]\!] \Gamma \rho & \stackrel{\triangle}{=} & \langle \mathcal{C}[\![e_1]\!] \Gamma \rho, \mathcal{C}[\![e_2]\!] \Gamma \rho \rangle \\ \mathcal{C}[\![\#\!1 \ e]\!] \Gamma \rho & \stackrel{\triangle}{=} & \pi_1(\mathcal{C}[\![e]\!] \Gamma \rho) \\ \mathcal{C}[\![\#\!2 \ e]\!] \Gamma \rho & \stackrel{\triangle}{=} & \pi_2(\mathcal{C}[\![e]\!] \Gamma \rho) \\ \mathcal{C}[\![\mathsf{inL}_{\tau_1 + \tau_2} \ e]\!] \Gamma \rho & \stackrel{\triangle}{=} & \mathsf{in}_1(\mathcal{C}[\![e]\!] \Gamma \rho) \\ \mathcal{C}[\![\mathsf{inR}_{\tau_1 + \tau_2} \ e]\!] \Gamma \rho & \stackrel{\triangle}{=} & \mathsf{in}_2(\mathcal{C}[\![e]\!] \Gamma \rho) \\ \mathcal{C}[\![\mathsf{case} \ e_0 \ \mathsf{of} \ e_1 \ | \ e_2]\!] \Gamma \rho & \stackrel{\triangle}{=} & \mathsf{case} \ \mathcal{C}[\![e_0]\!] \Gamma \rho \ \mathsf{of} \ \mathsf{inL} \ v \to (\mathcal{C}[\![e_1]\!] \Gamma \rho) \ v \ | \ \mathsf{inR} \ v \to (\mathcal{C}[\![e_2]\!] \Gamma \rho) \ v, \end{split}$$

where  $\pi_n$  is the (mathematical) projection operator that selects the *n*th element of a product and  $in_n$  is the injection operator that injects an element into a coproduct.

## 5 Adding Recursion

So far this language is not Turing-complete, because there is no way to do unbounded recursion. This is true because there is no possibility of nontermination. The easiest way to add this capability to the language is to add support for recursive functions.

To do this, we first extend the definition of an expression:

$$e ::= \cdots \mid \operatorname{rec} f: \sigma \to \tau . \lambda x: \sigma. e$$

The new keyword rec defines a recursive function named f such that both x and f are in scope inside e. Intuitively, the meaning of rec  $f: \sigma \to \tau . \lambda x: \sigma . e$  is the least fixpoint of the map  $f \mapsto \lambda x: \sigma . e$ , where both f and  $\lambda x: \sigma . e$  are of type  $\sigma \to \tau$ .

For example, we would write the recursive function

$$f(x) = \text{if } x > 0 \text{ then } 1 \text{ else } f(x+1)$$

as

$$\operatorname{rec} f:\operatorname{int} \to \operatorname{int} \lambda x:\operatorname{int.} \text{ if } x > 0 \text{ then } 1 \text{ else } f(x+1).$$

The small-step operational semantics evaluation rule for rec is:

$$\operatorname{rec} f : \sigma \to \tau \, . \, \lambda x : \sigma . \, e \quad \to \quad \lambda x : \sigma . \, e \left\{ (\operatorname{rec} f : \sigma \to \tau \, . \, \lambda x : \sigma . \, e) / f \right\}$$

and the typing rule for rec is

$$\frac{\Gamma, f: \sigma \to \tau, x: \sigma \vdash e: \tau}{\Gamma \vdash (\mathsf{rec} f: \sigma \to \tau. \lambda x: \sigma. e): \sigma \to \tau}$$

The denotational semantics is defined in terms of the fix operator on domains:

$$\mathcal{C}[\![\operatorname{rec} f : \sigma \to \tau \, . \, \lambda x : \sigma . \, e]\!] \, \Gamma \, \rho \quad \stackrel{\triangle}{=} \quad \operatorname{fix} \, \lambda g \in \mathcal{T}[\![\sigma \to \tau]\!] . \, \lambda v \in \mathcal{T}[\![\sigma]\!] . \, \mathcal{C}[\![e]\!] \, \Gamma[(\sigma \to \tau)/f, \, \sigma/x] \, \rho[v/x, g/f]$$

Of course, whenever we take a fixed point, we have to make sure that a fixed point exists. We know that the function satisfies continuity and monotonicity because we are writing in the metalanguage. However, for a fixed point to exist,  $\mathcal{T}[\![\sigma \to \tau]\!]$  must be a pointed CPO. But for this to be true, we have to make sure  $\perp$  is in the codomain of the function:

$$\mathcal{T}\llbracket \sigma \to \tau \rrbracket_{\perp} = \mathcal{T}\llbracket \sigma \rrbracket \to \mathcal{T}\llbracket \tau \rrbracket_{\perp},$$

We also have to change our contract to account for the possibility of nontermination:

$$\rho \models \Gamma \land \Gamma \vdash e : \tau \quad \Rightarrow \quad \mathcal{C}\llbracket e \rrbracket \Gamma \rho \in \mathcal{T}\llbracket \tau \rrbracket_{\perp}.$$

Finally, we have to lift our semantics to take nontermination into account. For example, we should change the denotation of a pair to:

$$\mathcal{C}\llbracket(e_1, e_2)\rrbracket\Gamma\rho \stackrel{\triangle}{=} \begin{cases} \langle \mathcal{C}\llbracket e_1 \rrbracket\Gamma\rho, \mathcal{C}\llbracket e_2 \rrbracket\Gamma\rho \rangle, & \text{if both } \mathcal{C}\llbracket e_1 \rrbracket\Gamma\rho \neq \bot \text{ and } \mathcal{C}\llbracket e_2 \rrbracket\Gamma\rho \neq \bot, \\ \bot, & \text{otherwise.} \end{cases}$$