CS412/413

Introduction to Compilers Radu Rugina

Lecture 29: More Instruction Selection 07 Apr 03

Outline

- · Tiles: review
- · Maximal munch algorithm
- Some tricky tiles
 - conditional jumps
 - instructions with fixed registers
- Dynamic programming algorithm

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Instruction Selection

- Current step: converting low-level intermediate code into abstract assembly
- Implement each IR instruction with a sequence of one or more assembly instructions
- DAG of IR instructions are broken into tiles associated with one or more assembly instructions

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Tiles



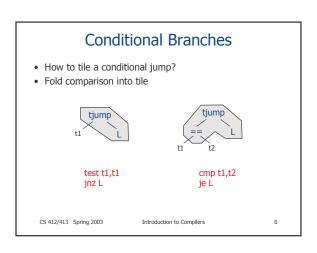
mov t1, t2 add \$1, t2

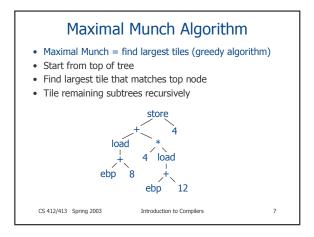
- Tiles capture compiler's understanding of instruction set
- Each tile: sequence of machine instructions that match a subgraph of the DAG
- May need additional move instructions
- Tiling = cover the DAG with tiles

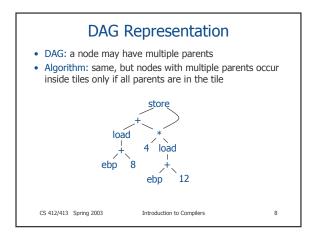
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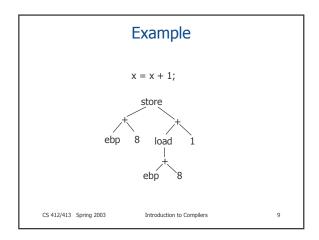
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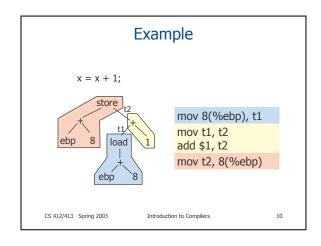
Tiles: Examples mov t2, t1 mov t2, t3 add t1, t3 add t1, t3 t1 mov t2, t3 add t1, t3 t1 mov t1, %eax mul t2 mov %eax, t3 t1 t2 mov %eax, t3 t1 t2

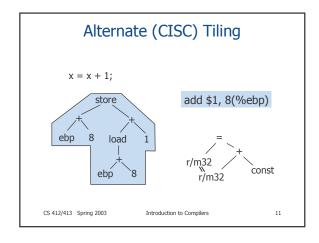


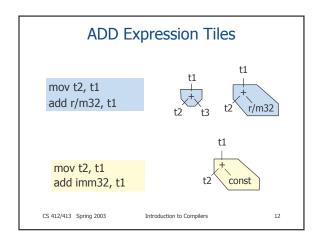


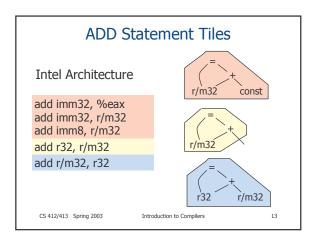


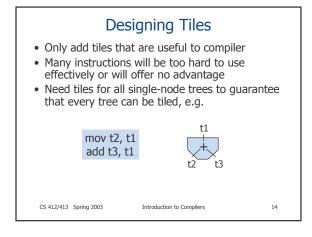


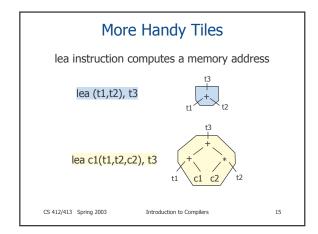


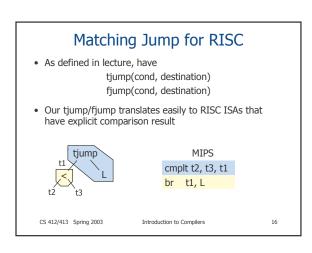


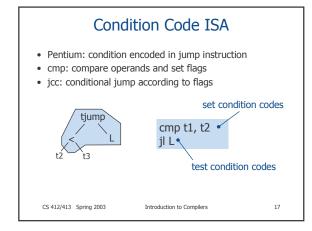












Fixed-register instructions mul r/m32 Multiply value in register eax Result: low 32 bits in eax, high 32 bits in edx jecxz L Jump to label L if ecx is zero add r/m32, %eax Add to eax • No fixed registers in low IR except frame pointer • Need extra move instructions CS 412/413 Spring 2003 Introduction to Compilers 18

Implementation

- Maximal Munch: start from top node
- Find largest tile matching top node and all of the children nodes
- Invoke recursively on all children of tile
- Generate code for this tile
- · Code for children will have been generated already in recursive calls
- · How to find matching tiles?

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21

23

```
Matching Tiles
          abstract class LIR_Stmt {
   Assembly munch();
          class LIR_Assign extends LIR_Stmt {
    LIR_Expr src, dst;
             Assembly munch() {
                 r/m32
                 else if ...
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```

Tile Specifications

- Previous approach simple, efficient, but hard-codes tiles and their priorities
- Another option: explicitly create data structures representing each tile in instruction set
 - Tiling performed by a generic tree-matching and code generation procedure
 - Can generate from instruction set description: code generator generators
 - For RISC instruction sets, over-engineering

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How Good Is It?

- Very rough approximation on modern pipelined architectures: execution time is number of tiles
- · Maximal munch finds an optimal but not necessarily optimum tiling
- · Metric used: tile size

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22

Improving Instruction Selection

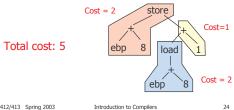
- · Because greedy, Maximal Munch does not necessarily generate best code
 - Always selects largest tile, but not necessarily the fastest instruction
 - May pull nodes up into tiles inappropriately it may be better to leave below (use smaller tiles)
- Can do better using dynamic programming algorithm

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Timing Cost Model

- Idea: associate cost with each tile (proportional to number of cycles to execute)
 - may not be a good metric on modern architectures
- · Total execution time is sum of costs of all tiles



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Finding optimum tiling

- Goal: find minimum total cost tiling of DAG
- Algorithm: for every node, find minimum total cost tiling of that node and sub-graph
- Lemma: once minimum cost tiling of all nodes in subgraph, can find minimum cost tiling of the node by trying out all possible tiles matching the node
- Therefore: start from leaves, work upward to top node

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Dynamic Programming: a[i]

mov 8(%ebp), t1
mov 12(%ebp), t2
mov (t1,t2,4), t3

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Recursive Implementation

- Dynamic programming algorithm uses memoization
- For each node, record best tile for node
- Start at top, recurse:
 - First, check in table for best tile for this node
 - If not computed, try each matching tile to see which one has lowest cost
 - Store lowest-cost tile in table and return
- Finally, use entries in table to emit code

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27

29

Memoization

```
class IR_Move extends IR_Stmt {
    IR_Expr src, dst;
    Assembly best; // initialized to null
    int optTileCost() {
        if (best != null) return best.cost();
        if (src instanceof IR_Plus &&
            ((IR_Plus)src).lhs.equals(dst) && is_regmem32(dst)) {
            int src_cost = ((IR_Plus)src).rhs.optTileCost();
            int cost = src_cost + CISC_ADD_COST;
            if (cost < best.cost())
            best = new AddIns(dst, e.target); }
            ...consider all other tiles...
            return best.cost();
    }
}
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```

Problems with Model

- Modern processors:
 - execution time not sum of tile times
 - instruction order matters
 - Processors pipeline instructions and execute different pieces of instructions in parallel
 - bad ordering (e.g. too many memory operations in sequence) stalls processor pipeline
 - processor can execute some instructions in parallel (super-scalar)
 - cost is merely an approximation
 - instruction scheduling needed

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Summary

- Can specify code generation process as a set of tiles that relate low IR trees (DAGs) to instruction sequences
- Instructions using fixed registers problematic but can be handled using extra temporaries
- Maximal Munch algorithm implemented simply as recursive traversal
- Dynamic programming algorithm generates better code, can be implemented recursively using memoization
- Real optimization will also require instruction scheduling

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5

30