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Introduction to Compilers Radu Rugina

Lecture 16: Intermediate Representation 24 Feb 03

Record Subtyping

• Width Subtyping: types of inherited fields must match in the subtype

$$\begin{array}{c} & n \leq m \\ A \vdash & \{a_1; \, T_1 \, , ..., \, a_m; \, T_m \, \} <: \, \{a_1; \, T_1 \, , ..., \, a_n; \, T_n \, \} \end{array}$$

 Depth subtyping: corresponding immutable fields may be subtypes; exact match not required

$$\begin{array}{c} A \; \vdash \; T_{i} <: \, T_{i} \, ' \, \, ^{(i \, \in \, 1..n)} \\ \\ A \vdash \{a_{1} \colon T_{1} \ldots \, a_{n} \colon T_{n}\} <: \, \{a_{1} \colon T_{1} ' \ldots \, a_{n} \colon T_{n} '\} \end{array}$$

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Depth Subtyping

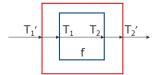
- Depth subtyping for objects:
 - Mutable components must be type invariant
 - Immutable components may be type covariant
- Immutable components:
 - Methods (but Java is conservative)
 - Constant fields: final in Java

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Function Subtyping

- Function subtyping: $T_1 \rightarrow T_2 <: T_1' \rightarrow T_2'$
- Consider function f of type T₁→T₂:



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Contravariance/Covariance

- Function argument types may be contravariant
- Function result types may be covariant

$$\begin{array}{c} T_{1}{'} <: T_{1} \\ \hline T_{2} <: T_{2}{'} \\ \hline T_{1} \rightarrow T_{2} <: T_{1}{'} \rightarrow T_{2}{'} \end{array}$$

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Java Array Subtyping

- Java has array type constructor: for any type T, T [] is an array of T's
- Java also has subtype rule:

$$T_1 <: T_2$$
 $T_1[] <: T_2[]$

Is this rule safe?

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Java Array Subtyping

• Example:

Elephant <: Animal
Animal [] x;
Elephant [] y;
x = y;
x[0] = new Rhinoceros(); // oops!</pre>

- · Covariant modification: unsound
- · Java does run-time check!

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Unification

• Some rules more problematic: if

• Rule: A |-- E : bool A |-- S₁ : T

A $|--S_2:T$ A $|--if(E)S_1$ else $S_2:T$

- Problem: if S_1 has type T_1 , S_2 has type T_2 . Old check: T_1 = T_2 . New check: need type T. How to unify T_1 , T_2 ?
- Occurs in Java: ?: operator

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General Typing Derivation

 $\frac{A \vdash E: bool \ \ \frac{A \vdash S_1: T_1 \quad T_1 <: T}{A \vdash S_1: T} \quad \frac{A \vdash S_2: T_2 \quad T_2 <: T}{A \vdash S_2: T}}{A \vdash if (E) S_1 else S_2: T}$

How to pick T?

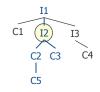
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Unification

- Idea: unified type is least common ancestor in type hierarchy (least upper bound)
- Partial order of types must be a lattice

if (b) new C5() else new C3(): I2



LUB(C3, C5) = I2

Logic: I2 must be same as or a subtype of any type (e.g. I1) that could be the type of both a value of type C3 and a value of type C5 What if no LUB?

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Summary: Semantic Analysis

- Check errors not detected by lexical or syntax analysis
- Scope errors:
 - Variables not defined
 - Multiple declarations
- Type errors:
 - Assignment of values of different types
 - Invocation of functions with different number of parameters or parameters of incorrect type
 - Incorrect use of return statements

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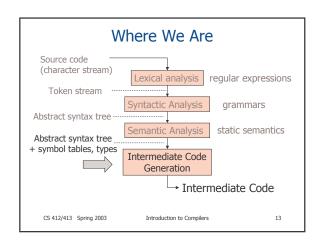
Semantic Analysis

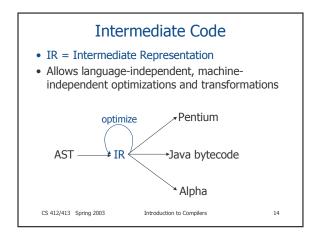
- Type checking
 - Use type checking rules
 - Static semantics = formal framework to specify typechecking rules
- There are also control flow errors:
 - Must verify that a break or continue statement is always enclosed by a while (or for) statement
 - Java: must verify that a break X statement is enclosed by a for loop with label X
 - Can easily check control-flow errors by recursively traversing the AST

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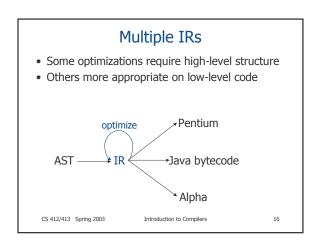
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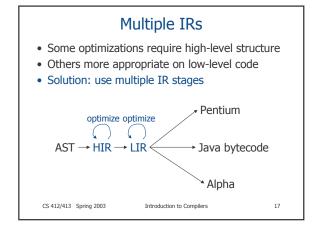
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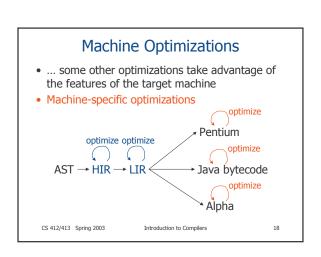




What Makes a Good IR? Easy to translate from AST Easy to translate to assembly Narrow interface: small number of node types (instructions) Easy to optimize Easy to optimize Easy to retarget AST (>40 node types) IR (13 node types) Pentium (>200 opcodes)

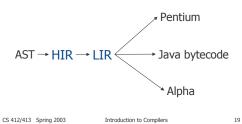


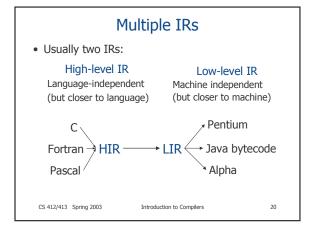






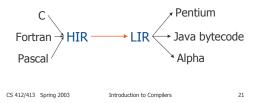
- Next few lectures: intermediate representation
- · Optimizations covered later





Multiple IRs

- Another benefit: a significant part of the translation from high-level to low-level is
 - Language-independent
 - Machine-independent



High-Level IR

- High-level intermediate representation is essentially the AST
 - Must be expressive for all input languages
- Preserves high-level language constructs
 - Structured control flow: if, while, for, switch, etc.

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- variables, methods
- Allows high-level optimizations based on properties of source language (e.g. inlining)

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Low-Level IR

- Low-level representation is essentially an abstract machine
- Has low-level constructs
 - Unstructured jumps, instructions
- Allows optimizations specific to these constructs (e.g. register allocation, branch prediction)

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Low-Level IR

- Alternatives for low-level IR:
 - Three-address code or quadruples (Dragon Book): a = b OP c
 - Tree representation (Tiger Book)
 - Stack machine (like Java bytecode)
- Advantages:
 - Three-address code: easier dataflow analysis
 - Tree IR: easier instruction selection
 - Stack machine: easier to generate

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Three-Address Code

• In this class: three-address code

$$a = b OP c$$

- Has at most three addresses (may have fewer)
- Also named quadruples because can be represented as: (a, b, c, OP)
- Example:

```
a = (b+c)*(-e);
                          t1 = b + c
                          t2 = -e
                          a = t1 * t2
```

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Low IR Instructions

- Assignment instructions:
 - Binary operations: a = b OP c
 - Arithmetic, logic, comparisons
 - Unary operation a = OP b
 - Arithmetic, logic
 - Copy instruction: a = b
 - Load /store: a = *b, *a = b
 - Other data movement instructions

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Low IR Instructions (Ctd)

- Flow of control instructions:
 - label L : label instruction
 - jump L : Unconditional jump
 - cjump a L : conditional jump
- Function call
 - call f(a₁,, a_n)
 - $a = call f(a_1,, a_n)$
 - Is an extension to quads
- ... IR describes the Instruction Set of an abstract machine

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Temporary Variables

- The operands in the quadruples can be:
 - Program variables
 - Integer constants
 - Temporary variables
- Temporary variables = new locations
 - Use temporary variables to store intermediate values

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Arithmetic / Logic Instructions

· Abstract machine supports a variety of different operations

$$a = b OP c$$

$$a = OPb$$

- Arithmetic operations: ADD, SUB, DIV, MUL
- Logic operations: AND, OR, XOR
- Comparisons: EQ, NEQ, LE, LEQ, GE, GEQ
- Unary operations: MINUS, NEG

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Data Movement

- Copy instruction: a = b
- Load/store instructions:

- Models a load/store machine
- Address-of instruction: a = &b
- Array accesses:

$$a = b[i]$$
 $a[i] = b$

• Field accesses:

a = b.fa.f = b

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Branch Instructions

• Label instruction:

label L

- Unconditional jump: go to statement after label L jump L
- Conditional jump: test condition variable a; if true, jump to label L

cjump a L

• Alternative: two conditional jumps:

tjump a L

fjump a L

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Call Instruction

• Supports function call statements

call
$$f(a_1, ..., a_n)$$

• ... and function call assignments:

$$a = call f(a_1, ..., a_n)$$

 No explicit representation of argument passing, stack frame setup, etc.

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Example

n = 0; while (n < 10) { n = n + 1 } n = 0label test t2 = n < 10t3 = not t2cjump t3 end label body n = n + 1jump test label end

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Another Example

m = 0; if (c == 0) { m = m+ n*n; } else { m = m + n; }



m = 0 t1 = c == 0 cjump t1 trueb m = m+n jump end label trueb t2 = n * n m = m + t2 label end

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How To Translate?

- May have nested language constructs
 - Nested if and while statements
- · Need an algorithmic way to translate
- Solution:
 - Start from the AST representation
 - Define translation for each node in the AST
 - Recursively translate nodes in the AST

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