

CS 412 Introduction to Compilers

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Lecture 24: Introduction to Optimization 30 Mar 01

Administration

- Programming Assignment 4 due Wednesday, April 4
- Optional reading: Muchnick 11

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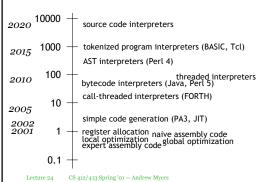
Optimization

- This course covers the most valuable and straightforward optimizations – much more to learn!
- Muchnick (optional text) has 10 chapters of optimization techniques

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How fast can you go?



Goal of optimization

- Help programmers
 - clean, modular, high-level source code
 - compile to assembly-code performance
- Optimizations are code transformations
 - must be safe; can't change meaning of program
- Different kinds of optimization:
 - space optimization: reduce memory use
 - time optimization: reduce execution time

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Where to optimize?

- Usual goal: improve time performance
- Problem: many optimizations trade off space versus time
- Example: loop unrolling
 - Increasing code space slows program down a little, speeds up one loop
 - Frequently executed code with long loops: space/time tradeoff is generally a win
 - Infrequently executed code: may want to optimize code space at expense of time
- Complex optimizations may never pay off!
- Want to optimize program hot spots

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Safety

• Opportunity for *loop-invariant code motion*:

```
while (b) {
    z = y/x; // x, y not assigned in loop
    ...
```

• Hoist invariant code out of loop:

- code transformation
- · safety of transformation
- · performance improvement

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Writing fast programs in practice

- Pick the right algorithms and data structures: reduce operations, memory usage, indirections
- Turn on optimization and *profile* to figure out program hot spots
- Evaluate whether design works; if so...
- Tweak source code until optimizer does "the right thing" to machine code

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Structure of an optimization

- Optimization is a code transformation
- Applied at some stage of compiler (HIR, MIR, LIR)
- In general requires some analysis:
 - safety analysis to determine where transformation does not change meaning (e.g. live variable analysis)
 - cost analysis to determine where it ought to speed up code (e.g. which variable to spill)

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When to apply optimization

```
AST
                              Inlining
Specialization
HIR
                              Constant folding
                              Constant propagation
                              Value numbering
                              Dead code elimination
             Canonical
MIR
                              Loop-invariant code motion
                  IR
                              Common sub-expression elimination
                              Strength reduction
                              Constant folding & propagation
Branch prediction/optimization
              Abstract
              Assembly
                              Register allocation
                              Loop unrolling
LIR
                              Cache optimization
              Assembly
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```

Why do we need optimization

- Programmers don't always write optimal code can recognize ways to improve code (e.g. avoid recomputing same expression)
- High-level language may make avoiding redundant computation inconvenient or impossible

$$a[i][j] = a[i][j] + 1$$

- Architectural independence
- Modern architectures assume optimization too hard to optimize by hand

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Register allocation

 Goal: convert abstract assembly (infinite no. of registers) into real assembly (6 registers)

```
mov t1, t2
add t1, [bp-4]
mov t3, [bp-8]
mov t4, t3
cmp t1, t4

mov ax, bx
add ax, [bp-4]
mov bx, [bp-8]
```

cmp ax, bx

- Need to reuse registers aggressively (e.g., bx)
- Want to coalesce registers (t3, t4) to eliminate mov's
- May be impossible without spilling to stack

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Constant folding

• Idea: if operands are known at compile time, evaluate at compile time.

```
int x = (2 + 3)*y; \Rightarrow
                              int x = 5*v:
b & false
                              false
```

- Performed at every stage of compilation
 - Constant expressions created by translation or optimization

```
a[2] \Rightarrow MEM(MEM(a) + 2*4)
      \Rightarrow MEM(MEM(a) + 8)
```

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Constant folding conditionals

```
if (true) S \Rightarrow S
if (false) S \Rightarrow :
if (true) S else S' \Rightarrow S
if (false) S else S' \Rightarrow S'
while (false) S \Rightarrow ;
if (2 > 3) S \Rightarrow ;
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```

Algebraic simplification

· More general form of constant folding: take advantage of usual simplification rules

```
a * 1 ⇒ a
                     a * 0 \Rightarrow 0
                                       identities
a + 0 \Rightarrow a
b \mid false \Rightarrow b
                             b & true \Rightarrow b
(a + 1) + 2 \Rightarrow a + (1 + 2) \Rightarrow a+3 reassociation
a * 4 \Rightarrow a shl 2
                                       strength reduction
a * 7 \Rightarrow (a shl 3) - a
a / 32767 \Rightarrow a shr 15 + a shr 30
```

• Must be careful with floating point!

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Unreachable code elimination

- Basic blocks not contained by any trace leading from starting basic block are unreachable and can be eliminated
- · Performed at canonical IR or assembly code levels
- Improves cache, TLB performance

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Inlining

• Replace a call to a function with the body of the function itself with args:

```
g(x: int):int = 1+ f(x);
f(a: int):int = (b:int=1; n:int = 0;
                while (n<a) (b = 2*b); b)
\Rightarrow g(x:int):int = 1 + (a:int = x; (b:int=1; n:int = 0;
                      while (n < a) (b = 2*b); b)
```

- May need to rename variables to avoid name capture—consider if f refers to a global var x
- · Can inline methods, but more difficult
- · Best done on HIR

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Specialization

Idea: create specialized versions of functions (or methods) that are called from different places w/ different args

```
class A implements I { m( ) {...} }
class B implements I { m( ) {...} }
                     // don't know which m
f(x: I) { x.m( ); }
                     // know A.m
a = new A(); f(a)
                     // know B.m
b = new B(); f(b)
```

- Can inline methods when implementation is known
- Impl known if only one implementing class

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Constant propagation

- If value of variable is known to be a constant, replace use of variable with constant
- Value of variable must be propagated forward from point of assignment

```
int x = 5;
int y = x*2;
int z = a[y]; // = MEM(MEM(a) + y*4)
```

• For full effect, interleave w/ constant folding

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Dead code elimination

• If side-effect of a statement can never be observed, can eliminate the statement

```
x = y*y; // dead!
... // x unused ... x = z*z; x = z*z;
```

· Variable is dead if never used after defn.

• Other optimizations create dead statements, variables

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Copy propagation

- Given assignment x = y, replace subsequent uses of x with y
- May make x a dead variable, result in dead code
- Need to determine where copies of y propagate to

```
x = y

if (x > 1)

x = x * f(x - 1)

Lecture 24 (x + 1) (x = y) if (y > 1) (y > 1)

(x = y) if (y > 1) (y - 1)
```

Redundancy Elimination

• Common Subexpression Elimination folds redundant computations together

$$a[i] = a[i] + 1$$

 $[[a]+i*4] = [[a]+i*4] + 1$
 $\Rightarrow t1 = [a] + i*4; [t1] = [t1]+1$

• Need to determine that expression always has same value in both places

```
b[j] = a[i] + 1; c[k] = a[i] \Rightarrow t1 = a[i]; b[j] = t1 + 1; c[k] = t1 ?
```

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Loops

- Program hot spots are usually loops (exceptions: OS kernels, compilers)
- Most execution time in most programs is spent in loops: 90/10 is typical
- Loop optimizations are important, effective, and numerous

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Loop-invariant code motion

- Another form of redundancy elimination
- If result of a statement or expression does not change during loop, and it has no externally-visible side-effect (!), can *hoist* its computation before loop
- Often useful for array element addressing computations – invariant code not visible at source level
- Requires analysis to identify loop-invariant expressions

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Example for (i = 0; i < a.length; i++) { // a not assigned in loop } hoisted loop-invariant expression t1 = a.length;for (i = 0; i < t1; i++) { ... }

Loop unrolling

• Branches are expensive; *unroll* loop to avoid them

```
for (i = 0; i < n; i++) { S }

for (i = 0; i < n-3; i+=4) {S; S; S; S;}

for ( ; i < n; i++) S;
```

- Gets rid of 3/4 of conditional branches!
- Space-time tradeoff: not a good idea for large *S* or small *n*.

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Summary

• Many useful optimizations that can transform code to make it faster

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- Whole is greater than sum of parts: optimizations should be applied together, sometimes more than once, at different levels
- Problem: when are optimizations are safe?
- ⇒Dataflow analysis
- ⇒Control flow analysis
- ⇒Alias analysis

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