



## CS 412 Introduction to Compilers

Andrew Myers  
Cornell University

Lecture 18: Finishing code generation  
9 Mar 01

## Outline

- Tiling as syntax-directed translation
- Implementing function calls
- Implementing functions
- Optimizing away the frame pointer
- Dynamically-allocated structures: strings and arrays
- Register allocation the easy way

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2

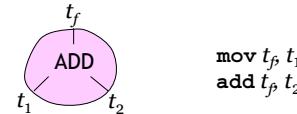
## Tiling, formally

- Each tile is really an inference rule!
- Write  $e \Rightarrow c$  (reg  $t$ )  
for “ $c$  is valid code for IR expression  $e$  that puts result into  $t$ ”
- Write  $s \Rightarrow c$   
for “ $c$  is valid code for IR statement  $s$ ”
- Translation is not a function of  $e/s$  : many possible translations (unlike  $\mathcal{T}[e]$ ,  $\mathcal{S}[e]$ , etc.)
  - translation *relation* generalizes translation function
  - can apply to earlier translations too – but less payoff

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## Expression tile as rule



`mov tf t1`  
`add tf t2`

$e_1 \Rightarrow c_1 \text{ (reg } t_1)$   
 $e_2 \Rightarrow c_2 \text{ (reg } t_2)$

$\overline{ADD(e_1, e_2) \Rightarrow c_1; c_2; \text{mov } t_f, t_1; \text{add } t_f, t_2 \text{ (reg } t_f)}$

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## Statement tiles as rules

$$\frac{\begin{array}{c} e_1 \Rightarrow c_1 \text{ (reg } t_1) \\ e_2 \Rightarrow c_2 \text{ (reg } t_2) \end{array}}{\overline{MOVE(MEM(e_1), e_2) \Rightarrow c_1; c_2; \text{mov } [t_1], t_2}}$$

$$\frac{e_1, e_2 \Rightarrow op_1 \text{ (r/m32)}}{\overline{MOVE(e_1, e_2 + CONST(k)) \Rightarrow add op_1, k}}$$

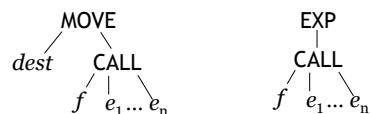
Inference rules are *not* syntax-directed – need heuristic or dynamic programming to choose

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5

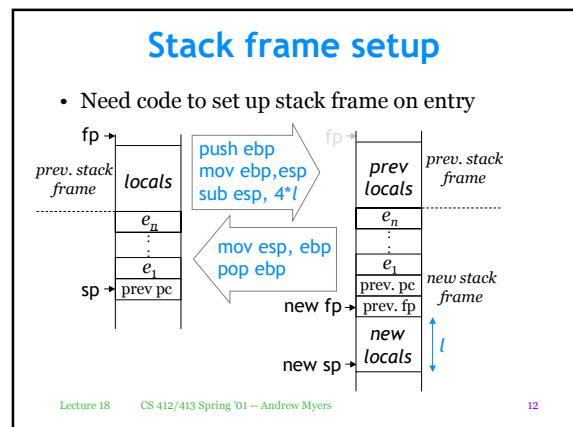
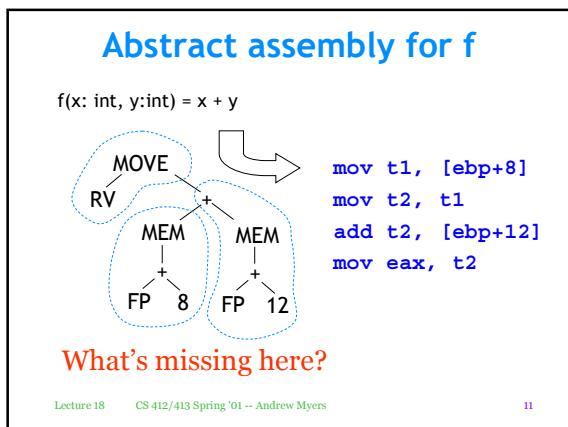
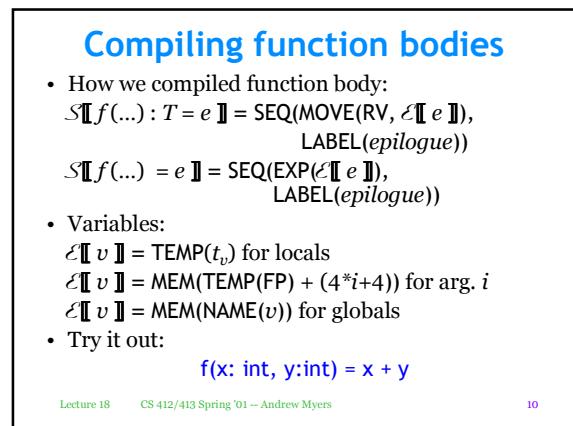
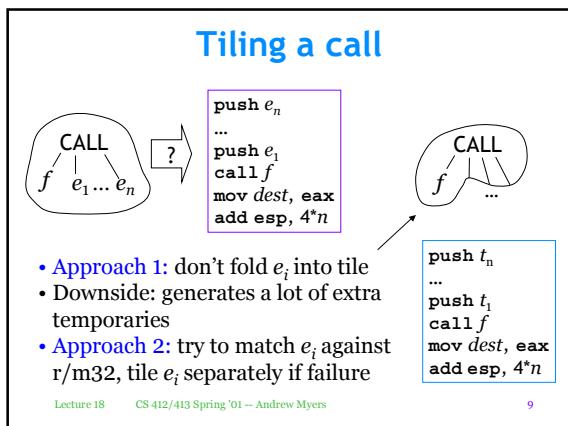
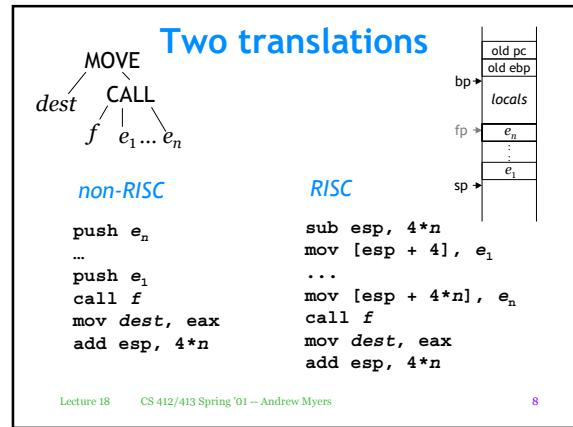
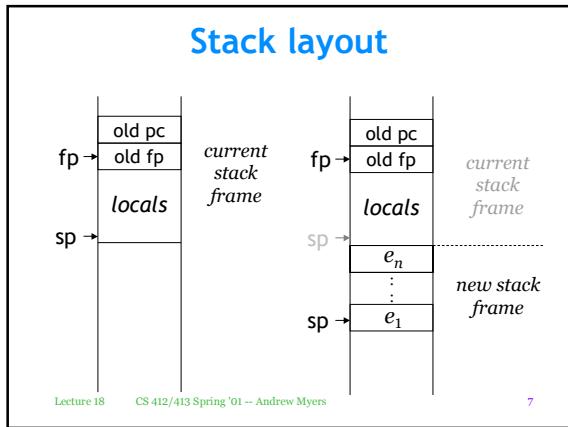
## Function calls

- How to generate code for function calls?
- Two kinds of IR statements in canonical form



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6



## Function code

```
f: push ebp
  mov ebp,esp
  sub esp, 4*I } function prologue
  mov t1, [ebp+8]
  mov t2, t1
  add t2, [ebp+12]
  mov eax, t2
f_epilogue:
  mov esp, ebp
  pop ebp
  ret } function epilogue
```

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## The Glory of CISC

```
f: push ebp
  mov ebp,esp
  sub esp, 4*I } enter 4*I, 0
  mov t1, [ebp+8]
  mov t2, t1
  add t2, [ebp+12]
  mov eax, t2
f_epilogue:
  mov esp, ebp } f_epilogue:
  pop ebp } leave
  ret }
```

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## Calling conventions

- Have described standard C calling convention
  - arguments pushed on stack, in reverse order
  - caller cleans up arguments
- stdcall: callee cleans up, MIPS/Alpha: first 4/6 arguments passed in registers
- Choice of caller- vs. callee-save:
  - caller-save: caller must save registers if needed after call; usable freely (`e[acd]x`)
  - callee-save: function not allowed to change; to use, must be saved (`e[sd]i, e[sb]p, ebx`)

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15

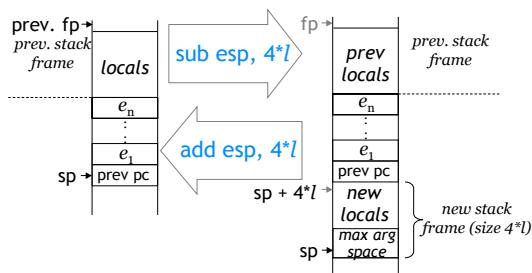
## Optimizing away ebp

- No need for frame pointer register!
- Idea: maintain constant offset  $k$  between frame pointer and stack pointer
  - Use RISC-style argument passing rather than pushing arguments on stack
  - All references to `MEM(FP+n)` translated to operand `[esp+(n+k)]` instead of `[ebp+n]`
- Advantage: get whole extra register to use when allocating registers (7!)

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## Stack frame setup



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## Caveats

- Get even faster (and RISC-core) prologue and epilogue than with `enter/leave` but:
- To avoid breaking callers, must save `ebp` register if we want to use it (callee-save)
- Doesn't work if stack frame is truly variable-sized
  - `alloca(n)` call in C allocates  $n$  bytes *on the stack* – compiler cannot predict
  - not a problem in Iota: arrays heap-allocated, stack frame has constant size

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18

## Dynamic structures

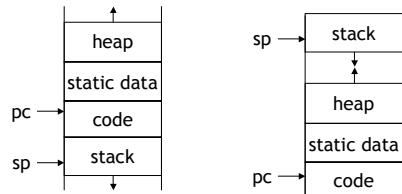
- Modern programming languages allow dynamically allocated data structures: strings, arrays, objects
- C:** `char *x = (char *)malloc(strlen(s) + 1);`
- C++:** `Foo *f = new Foo(...);`
- Java:** `Foo f = new Foo(...);`
- `String s = s1 + s2;`
- Iota:** `x: array[int] = new int[5] (0);`
- `String s = s1 + s2;`

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## Program Heap

- Program has 4 memory areas: code segment, stack segment, static data, heap
- Two typical virtual memory layouts (depends on OS):

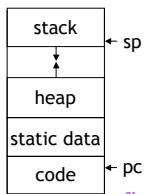


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20

## Object allocation

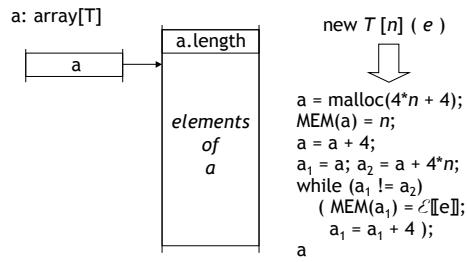
- Dynamic objects allocated in the heap
  - array creation, string concatenation
  - `malloc(n)` returns new chunk of  $n$  bytes, `free(x)` releases memory starting at  $x$
- Globals statically allocated in data segment
  - global variables
  - string constants
  - assembler supports data segment declarations



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## Iota dynamic structures



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## Trivial register allocation

- Can convert abstract assembly to real assembly easily (but generate bad code)
- Allocate every temporary to location in the current stack frame rather than to a register
- Every temporary stored in different place - no possibility of conflict
- Three registers needed to shuttle data in and out of stack frame (max. # registers used by one instruction) : e.g., eax, ecx, edx

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## Rewriting abstract code

- Given instruction, replace every temporary in instruction with one of three registers `e [acd] x`
  - Add `mov` instructions before instruction to load registers properly
  - Add `mov` instructions after instruction to put data back onto stack (if necessary)
- `push t1`  $\Rightarrow$  `mov eax, [fp - t1off]; push eax`  
`mov [fp+4], t3`  $\Rightarrow$  ?  
`add t1, [fp - 4]`  $\Rightarrow$  ?

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## Result

- Simple way to get working code
- Code is longer than necessary, slower
- Also can allocate temporaries to registers until registers run out (3 temporaries on Pentium, 20+ on MIPS, Alpha)
- Code generation technique actually used by some compilers when all optimization turned off (-OO)
- Will use for Programming Assignment 4

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25

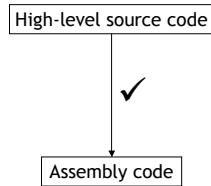
## Summary

- Complete code generation technique
- Use tiling to perform instruction selection
- Arguments mapped to stack locations, locals to temporaries
- Function code generated by gluing prologue, epilogue onto body
- Dynamic structure allocation handled by relying on heap allocation routines (malloc)
- Static structures allocated by data segment assembler declarations
- Allocate temporaries to stack locations to eliminate use of unbounded # of registers
- Shuttle temporaries in and out using e[acd]x regs

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26

## Where we are



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27