

CS211, LECTURE 25

MORE GRAPHS

ANNOUNCEMENTS:

- office hours today (Tues): 1-3pm
- A6 due Weds 4/30
- makeup assignment (“A7”) info
- bonus points on prelim?

OVERVIEW:

- implicit graph reminder
- explicit graphs
- adjacency matrix and list representations
- design, algorithms and implementation for basic classes
- building graphs

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1. Motivation

1.1 Up To Today:

- graph theory, which leads to ...
- implicit graphs and help with homework, then...
- explicit graphs to help build generic graph classes...
- build graphs

1.2 What To Do With Graphs?

- next two lectures...
- generalize traversal: BFS, DFS
- use traversal for searching
- sorting
- shortest path to something
- more...?

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2. Representations

2.1 Implicit

- rules/model creates a network of nodes/edges
- ex) puzzle moves
 - each move makes a new puzzle
 - treat each state as a node
 - so, rules implicit define a graph
- common for games!

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2.2 Explicit

- define all nodes V and edges E ahead of time
- want system to represent edges
- why? it's the “biggest problem”:
 - $G = (V, E)$ and each edge e in E is a pair (v_1, v_2)
 - most edges possible? $|V|^2$
(form pairs from all nodes)
 - most sets of edges possible? $2^{|V|^2}$
- so, use container to represent edges
 - adjacency matrix
 - adjacency list

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2.3 Adjacency Matrix

- **adjacency matrix**

$$A_{ij} = \begin{cases} w_{ij} & \{v_i, v_j\} \in E \\ 0 & \text{otherwise} \end{cases}$$

- terms

v_i : node i; v_j node j

$\{v_i, v_j\} \in E$: edge between nodes i (v_i) and j (v_j)

belongs to set of edges E

w_{ij} : weight of edge between nodes i and j

- A_{ij} : the matrix (rectangular 2x2 array) as rows (i) and cols (j); coords correspond to nodes i and j

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2.4 Adjacency List

- adjacency list: linked list of nodes adjacent to a node
- need $|V|$ lists

2.5 graph types to develop:

- undirected
- directed
- weighted

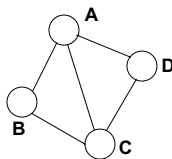
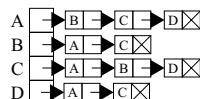
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2.6 Undirected

$$A_{ij} = \begin{cases} 1 & \{v_i, v_j\} \in E \\ 0 & \text{otherwise} \end{cases}$$

i \ j	A	B	C	D
A		1	1	1
B	1		1	
C	1	1		1
D	1		1	

Use array A of lists:
 A_i stores a linked list of nodes
 no edge implied by order *in* list
 nodes must be adjacent to A_i



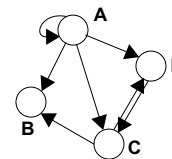
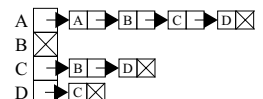
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2.7 Directed

$$A_{ij} = \begin{cases} 1 & (v_i, v_j) \in E \\ 0 & \text{otherwise} \end{cases}$$

i \ j	A	B	C	D
A	1	1	1	1
B				
C		1		1
D			1	

Use array A of lists:
 A_i stores a linked list of nodes
 no edge implied by order *in* list
 nodes must be adjacent to A_i



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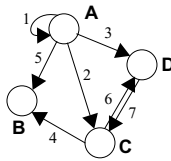
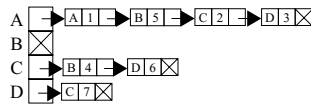
2.8 Weighted

- assuming also weighted
- w_{ij} : cost or weight of edge from node i to node j
- sometimes use sentinel ∞ to represent “no edge” between i and j

$$A_{ij} = \begin{cases} w_{ij} & (v_i, v_j) \in E \\ 0 & \text{otherwise} \end{cases}$$

Use array A of lists: include weights
List for i contains j, w for edge (i, j)

i \ j	A	B	C	D
A	1	5	2	3
B				
C		4		6
D			7	



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2.9 Choice of AM or AL?

- Adjacency Matrix
 - uses $O(|V|^2)$ space
 - can answer “is there an edge from i to j ?” in $O(1)$ time
 - enumerating all nodes adjacent to i : $O(|V|)$ (find all nodes j in row for i)
 - could be sparse because of wasted space (0s)
 - better for dense graphs (lots of edges)!
- Adjacency List
 - uses $O(|V|+|E|)$ space ($|V|$ for i nodes, $|E|$ for j nodes emanating from each i node)
 - can answer question “is there an edge from i to j ?” in $O(|E|)$ time
 - enumerating all nodes adjacent to i : $O(1)$ per adjacent node in linked list
 - better for sparse graphs (few edges)!

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3. Implementation

3.1 Implicit

- can use containers to store node and edge info
- a bit too problem specific, though effective

3.2 Explicit

- Adjacency Matrix - left as exercise
- Adjacency List
 - using linked list to allow for flexible building
 - kind of gives implicit building by allowing for node/edge creation “on the fly”
- focus on digraph, but could be weighted
 - Sections 3, 4, 5, 6
 - many methods left out – will see for graph problems

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4. Vertices

4.1 Fields

- **label**: we like to have names, numbers, ...
- **edges**: collection of all emanating edges from the current vertex
- **visited**: need later to tag vertex for searching...
- sometimes includes **cost** (cost to get *here* from somewhere)

4.2 Constructor

- set **label**
- create **edges** adjacency list (AL)

4.3 Methods

- **addEdge**: add to AL
- **equals**: need for path checking
- more?

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```

import java.util.*;

public class Vertex {

    private Object label;
    private LinkedList edges; // adjacent edges
    private boolean visited; // tag

    public Vertex(Object o) {
        label = o;
        edges = new LinkedList();
    }

    public void addEdge(Edge e, int weight) {
        Vertex source = this;
        Vertex dest = e.getDest();
        edges.add(new Edge(source,dest,weight));
    }

    public void addEdge(Edge e) {
        addEdge(e,0);
    }

    public boolean equals(Vertex other) {
        return label.equals( ((Vertex)other).label );
    }

    public String toString() {
        return label.toString();
    }

    public Collection getEdges() { return edges; }
} // Class Vertex

```

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5. Edges

5.1 Fields

- source: s->d, the node from which edge emanates
- dest: actually, all you need is this since Vertex keeps track of adjacent edges of source
- weight: could make double (sometimes called cost)

5.2 Constructors

- build edge from s->d
- can default to weight of 0 to handle unweighted graphs

5.3 Methods

- **equals** and **compareTo**:
 - many algorithms want to know shortest path
 - need to compare costs of going in different directions
- **toString**: "source-weight->dest"
- more?

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```

public class Edge implements Comparable {

    private Vertex source; // s (s->d)
    private Vertex dest;   // d
    private int weight;     // also called cost

    public Edge(Vertex source, Vertex dest, int weight) {
        this.source=source;
        this.dest=dest;
        this.weight=weight;
    }

    public Edge(Vertex source, Vertex dest) {
        this(source,dest,0);
    }

    // getters and setters not shown

    public boolean equals(Object other) {
        Edge e = (Edge) other;
        return weight == e.weight;
    }

    public int compareTo(Object other) {
        Edge e = (Edge) other;
        return (int) (weight-e.weight);
    }

    // Stringify as (d,--w->,s):
    public String toString() {
        return "("+source+"-"+weight+"->"+dest+")";
    }
} // Class Edge

```

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6. Directed Graphs

6.1 Fields

- **verticies** dictionary:
 - key-val pairs of (VertexName,Vertex)
 - each Vertex points to its adjacency list!
- **edgeCount**

6.2 Constructors

- set **verticies** to LinkedHashMap
- maintains order of nodes in order created
- nodes *must* be created before edges this way!

6.3 Methods

- use vertex names/labels!
- **addVertex**: put **Vertex** in **Map**: (name, Vertex)
- **addEdge**: connect s and d nodes (they must exist!)

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```

import java.util.*;
public class Digraph {

    private Map vertices; // dictionary of nodes
    private int edgeCount; // number of edges

    public Digraph( ) {
        vertices = new LinkedHashMap();
    }

    // Add vertex to map
    public void addVertex(Object name) {
        vertices.put(name, new Vertex(name));
    }

    // Adds edge (source and dest node must exist!):
    public void addEdge(Object s, Object d, int weight) {

        // Key is NAME of Vertex
        // Val is THE Vertex
        // So, get keys of s and d and use them to
        //     retrieve their vals (their Vertices):
        Vertex source = (Vertex)vertices.get(s);
        Vertex dest = (Vertex)vertices.get(d);

        // Create edge between source and dest:
        s.addEdge(new Edge(source,dest,weight));
        edgeCount++;
    }

    public void addEdge(Object source, Object dest) {
        addEdge(source,dest,0);
    }
}

```

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```

// Stringify: return edges with
//     their adjacency lists:
public String toString() {

    String s = "";

    Iterator it=vertices.keySet().iterator();

    while(it.hasNext()) {

        // current node label:
        Object key = it.next();

        // current Vertex:
        Vertex val = (Vertex) vertices.get(key);

        // build string for current vertex in Map:
        s += "[" + val + "]" + "-->";
        s += val.getEdges();
        s += "\n";

    }

    return s;

} // Method toString

} // Class Digraph

```

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7. Demonstration

7.1 Code

```

public class TestDigraph {

    public static void main(String[] args) {

        Digraph g = new Digraph();
        g.addVertex("A");
        g.addVertex("B");
        g.addVertex("C");
        g.addEdge("A","B");
        g.addEdge("A","C");
        g.addEdge("B","C");
        System.out.println(g);

    }
}

```

7.2 Output

```

[A]-->[(A-0->B), (A-0->C)]
[B]-->[(B-0->C)]
[C]-->[]

```

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8. Exercises

- Demonstrate why we use edges for explicit representations of graphs.
- Develop **Vertex**, **Edge**, **Digraph**, and **TestDigraph** classes for the adjacency matrix approach. You should develop methods to handle I/O in reading in a grid of adjacencies to help build a graph.
- Remove the **source** node field from class **Edge** and modify the remaining classes as necessary. This design is a bit more common than the examples given to you.
- Rewrite **Digraph**'s **addEdge** such that it does not assume that the nodes exist. You may either throw an exception or perhaps create more nodes....
- Graphical graph: This was once a final project long ago...develop a GUI tool that draws a graph that a user creates, either via the GUI or as a translation from the collection that contains the vertices and edges. A rudimentary application would naively draw each vertex according to a pre-determined grid and then draw the edges using the given vertex geometry.

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