

CS 412/413
 Introduction to
Compilers and Translators
 Andrew Myers
 Cornell University

Lecture 29: More optimizations
 10 April 00

Outline

- Loop optimizations
 - Loop-invariant code motion
 - Strength reduction
 - Loop unrolling
 - Array bounds checks
- Eliminating null checks
- Alias analysis
- Incremental dataflow analysis

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Dominator data-flow analysis

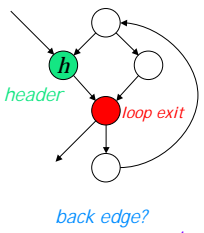
- **A dom B** if **B** is reachable only by going through **A**.
- Forward analysis; $out[n]$ is set of nodes dominating n
- “**A dom B** only if **A** dominates *all* predecessors of **B**”

$L = \text{sets of nodes ordered by } \subseteq$
 $\sqcap = \cap$
 $T = \{\text{all } n\}$
 $F_n(x) = x \cup \{n\}$

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Dominators and loops

- Defn of loop: set of strongly-connected nodes with single entry point: *loop header* node
- *loop header* dominates all other nodes in loop
- Loop must contain *back edge* w/ respect to dominance relationship: $n \rightarrow h$ where $h \text{ dom } n$

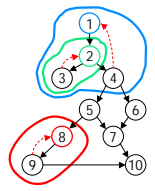


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Completing control-flow analysis

- Dominator analysis gives all *back edges*
- Each back edge $n \rightarrow h$ has an associated *natural loop* with h as its header: all nodes reachable from h that reach n without going through h
- For each back edge, can find its natural loop:

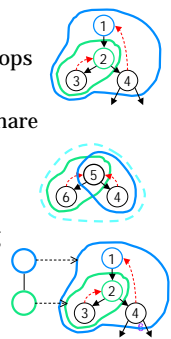
$\{n' \mid n' \text{ reachable from } h\} \cap$
 $\{n' \mid n \text{ reachable from } n' \text{ in } G-h\}$



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Control tree

- Nest loops based on subset relationship between natural loops
- Exception: natural loops may share same header; merge them into larger loop.
- Build control tree using nesting relationship



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Redundant computation

```
for (int i=0; i<a.length; i++) {
    a[i] = a[i]+1;
}
```

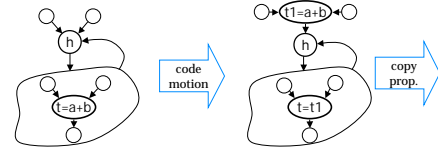
<pre> i=0 L0: t0=a-4 tlen=[t0] tcmp=i<t0 if tcmp goto Lend else L1 L1: t1=i*4 t2=a+t1 t0=a-4 tlen=[t0] tcmp=i<t0 if tcmp goto Lok1 else LA1 LA1: abort </pre>	<pre> Lok1: t3=i*4 t4=a+t3 t0=a-4 tlen=[t0] tcmp=i<t0 if tcmp goto Lend else L1 L1: t3=[t2] [t1]=t3 t2=t2+4 t1=t1+4 i=i+1 goto L0 </pre>	<pre> t0=a-4 tn=[t0] t1=a t2=a+4 L0: i=0 tcmp=i<tn if tcmp goto Lend else L1 L1: t3=[t2] [t1]=t3 t2=t2+4 t1=t1+4 i=i+1 goto L0 </pre>
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Loop-invariant hoisting

- *Idea*: move computations that always give the same result out of the loop: only compute once!
- Hoisting $a + b$: a or b must be
 - constant,
 - only defined outside loop (use *reaching definitions*),
 - or only one definition inside loop whose expression is loop-invariant
- Can identify all loop-invariant exprs in one pass



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Induction variables

- *Induction variables* are variables with value $ai + b$ on the i^{th} iteration of a natural loop, for constants a & b
- Various optimizations can exploit information about induction variables:
 - strength reduction
 - array bounds check elimination
 - loop unrolling

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Identifying induction variables

- *Basic induction variables*: only one definition of the form $i = i + K$
- *Derived induction variables*: value is $i * M + N$ for some b.i.v. i

```

j = 3;
for (i = 0; i < n; i++) {
    j = j + 1;
    k = i*4 + 8;
    m = k*12 + j*2;
    ...
}
        
```

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Strength reduction

- Every derived induction variable k can be written as $a*i + b$, a and b constants, i some basic induction variable
- For all distinct (a, b) pairs:
 - insert before loop header $k' = b$
 - insert after loop header $k' = k' + a$
 - Replace definition of any k whose formula is $a*i + b$ with $k = k'$
- Result: multiplication(s) replaced by single addition

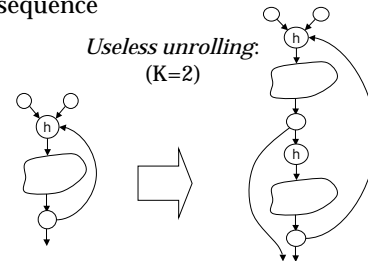
 $t1=i*4 \Rightarrow t1=t1+4$
- Additional optimizations facilitated: copy/constant propagation, dead variable elimination, dead code elimination

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Loop unrolling

- Loop unrolling: creates K copies of loop in sequence

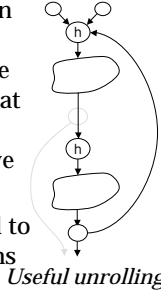


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Using induction variables

- When loop test expression depends on induction variable (e.g. $i < n$), can use one loop test to ensure that entire unrolled loop will succeed ($i+K-1 < n$): remove all interior loop tests
- Additional loop is needed to "finish up" $0..K-1$ iterations



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Array bounds checks

- Iota+: On every expression $a[i]$, must ensure $i < \text{length } a$, $i \geq 0$ ($i <_u \text{length } a$)
- Checking array bounds is expensive
- Array indices are often induction variables -- can use induction variable information to avoid the bounds check entirely!
- Can eliminate the bounds check if we can prove at compile time that it will always succeed

```
for (int i=0; i<a.length; i++) {
    a[i] = a[i+1];
}
```

two unnecessary bounds checks

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Rules

- Given reference $a[k]$ where k is an induction variable with value $a*i + b$, must find a conditional test on some induction variable j
 - test terminates the loop
 - test dominates the reference to $a[k]$
 - test is against some loop invariant such that provably $k <_u a.\text{length}$
- When to perform optimization?
 - AST? Need domination analysis, other optimizations not done.
 - Quadruples? Hard to recognize array length, array accesses. Must propagate annotations.

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Null checks

- Another costly operation: checking for null pointers
- Java, Iota+ : needed on every
 - field access or assignment (except on this)
 - method invocation (except on this)
 - array element access
 - string operation
- Idea: Once we've checked for null, shouldn't need to check again

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Example

$u = p.x + p.y$

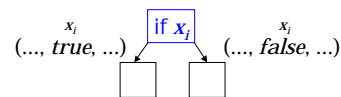
\Rightarrow	<code>t1 = p != 0</code>	<code>t1 = p != 0</code>
	<code>if t1 goto L1 else L2</code>	<code>if t1 goto L1 else L2</code>
	<code>L2: abort</code>	<code>L2: abort</code>
	<code>L1: ax = p + 4</code>	<code>L1: ax = p+4</code>
	<code>tx = M[ax]</code>	<code>tx = M[ax]</code>
	<code>t2 = p != 0</code>	<code>t2 = t1</code>
	<code>CSE: t2 = t1</code>	<code>Copy: if t1 goto ...</code>
	<code>if t2 goto L3 else L4</code>	<code>Bool: t1 = true</code>
	<code>L3: abort</code>	<code>goto L4</code>
	<code>L4: ay = p + 8</code>	<code>L3: abort</code>
	<code>ty = M[ay]</code>	<code>L4: ay = p + 8</code>
	<code>u = tx + ty</code>	<code>ty = M[ay]</code>
		<code>u = tx + ty</code>

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Boolean propagation

- Augment constant propagation with propagation of booleans
- Almost fits into standard dataflow analysis model
 - different information leaves on different out-edges of if statements



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Finishing optimization

t1 = p != 0	t1 = p != 0	CJUMP p != 0, L1
if t1 goto L1 else L2	if t1 goto L1 else L2	ABORT
L2: abort	L2: abort	L1: MOVE(u, M[p+4]
L1: ax = p+4	L1: ax = p+4	+ M[p+8])
tx = M[ax]	tx = M[ax]	
t2 = t1		
goto L4		
L3: abort		
L4: ay = p + 8	ay = p + 8	
ty = M[ay]	ty = M[ay]	
u = tx + ty	u = tx + ty	

$u = p.x + p.y$

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Memory accesses

- Memory operations are expensive, confuse optimizer
 - want to use CSE to eliminate extra reads whenever possible
 - converting [t] to temporary makes many optimizations more effective
- Problem: *kill*[n] for statement [a] = b:

[a]=b	<i>gen</i>	<i>kill</i>
	b	[t]
		(for all t that might be equal to a)

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Aliasing

- Problem: don't know when two memory operands might refer to same location (*alias* one another)
- Flow-insensitive alias analysis: "x may alias y"
- Flow-sensitive alias analysis: "x may alias y at program point (flowgraph edge) p"
- Key: exploit high-level language knowledge
 - stack and heap locations cannot be aliases
 - objects of unrelated types cannot be aliases
- Alias analysis: for each node, variable x, determine which things [x] might alias

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